

第4章：過渡現象

4.4 過渡現象の解法

キーワード：*RLC*直列回路

学習目標：*RLC*直列回路の過渡現象を解くことができるようになる。

4 過渡現象

4.4.5 RLC直列回路

[問題46]

$$L \frac{di}{dt} + Ri + \frac{1}{C} \int i dt = E$$

$i = \frac{dq}{dt}$ の関係を用いると

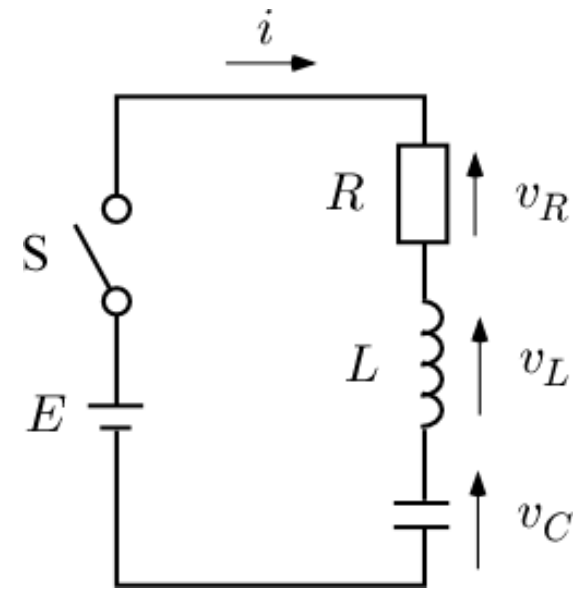
$$L \frac{d^2q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q = E$$

定常解

$$\underbrace{L \frac{d^2q_s}{dt^2}}_{=0} + \underbrace{R \frac{dq_s}{dt}}_{=0} + \frac{1}{C} q_s = E$$

$$\frac{1}{C} q_s = E$$

$$q_s = CE$$



過渡解

$$L \frac{d^2 q_t}{dt^2} + R \frac{dq_t}{dt} + \frac{1}{C} q_t = 0$$

$$q_t = Ae^{pt} \text{ とおく}$$

$$LAp^2 e^{pt} + RApe^{pt} + \frac{1}{C} Ae^{pt} = 0$$

$$\left(Lp^2 + Rp + \frac{1}{C} \right) Ae^{pt} = 0$$

よって

$$Lp^2 + Rp + \frac{1}{C} = 0$$

が成り立つ

$$p_1, p_2 = \frac{-R \pm \sqrt{R^2 - 4\frac{L}{C}}}{2L}$$

> 0 (1) 異なる2実数根を持つ場合

$= 0$ (2) 重根を持つ場合

< 0 (3) 虚数根を持つ場合

$$\frac{dq_t}{dt} = Ape^{pt}$$

$$\frac{d^2 q_t}{dt^2} = Ap^2 e^{pt}$$

$$\begin{aligned}
p_1, p_2 &= \frac{-R \pm \sqrt{R^2 - 4\frac{L}{C}}}{2L} = -\frac{R}{2L} \pm \sqrt{\frac{R^2}{(2L)^2} - 4\frac{L}{C(2L)^2}} \\
&= -\boxed{\frac{R}{2L}} \pm \sqrt{\boxed{\left(\frac{R}{2L}\right)^2} - \boxed{\frac{1}{LC}}} \quad \alpha = \frac{R}{2L}, \omega_0 = \frac{1}{\sqrt{LC}} \\
&\quad \quad \quad = \alpha \quad \quad \quad = \alpha^2 \quad \quad \quad = \omega_0^2
\end{aligned}$$

(1) 異なる2実数根と持つ場合 $\left(R^2 > \frac{4L}{C}\right)$

$$p_1, p_2 = -\frac{R}{2L} \pm \sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

$$\begin{aligned}
q_t &= A_1 e^{p_1 t} + A_2 e^{p_2 t} \\
&= A_1 e^{(-\alpha + \sqrt{\alpha^2 - \omega_0^2})t} + A_2 e^{(-\alpha - \sqrt{\alpha^2 - \omega_0^2})t} \\
&= e^{-\alpha t} \left(A_1 e^{(\sqrt{\alpha^2 - \omega_0^2})t} + A_2 e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right)
\end{aligned}$$

一般解

$$q = q_s + q_t \quad (\text{定常解} + \text{過渡解})$$

$$= CE + e^{-\alpha t} \left(A_1 e^{(\sqrt{\alpha^2 - \omega_0^2})t} + A_2 e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right) \quad (1-1)$$

$$\begin{aligned} i = \frac{dq}{dt} &= -\alpha e^{-\alpha t} \left(A_1 e^{(\sqrt{\alpha^2 - \omega_0^2})t} + A_2 e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right) \\ &\quad + e^{-\alpha t} \left(A_1 \sqrt{\alpha^2 - \omega_0^2} e^{(\sqrt{\alpha^2 - \omega_0^2})t} - A_2 \sqrt{\alpha^2 - \omega_0^2} e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right) \\ &= e^{-\alpha t} \left[A_1 \left(-\alpha + \sqrt{\alpha^2 - \omega_0^2} \right) e^{(\sqrt{\alpha^2 - \omega_0^2})t} \right. \\ &\quad \left. + A_2 \left(-\alpha - \sqrt{\alpha^2 - \omega_0^2} \right) e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right] \end{aligned} \quad (1-2)$$

初期条件 $t = 0, q = 0, i = 0$

(1-1)式に $t = 0, q = 0$ を代入

$$q = CE + e^{-\alpha t} \left(A_1 e^{(\sqrt{\alpha^2 - \omega_0^2})t} + A_2 e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right) \quad (1-1)$$

$$0 = CE + e^0 (A_1 e^0 + A_2 e^0)$$

$$A_1 + A_2 = -CE$$

$$A_2 = -A_1 - CE \quad (1-3)$$

(1-2)式に $t = 0, i = 0$ を代入

$$i = e^{-\alpha t} \left[A_1 \left(-\alpha + \sqrt{\alpha^2 - \omega_0^2} \right) e^{(\sqrt{\alpha^2 - \omega_0^2})t} + A_2 \left(-\alpha - \sqrt{\alpha^2 - \omega_0^2} \right) e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right] \quad (1-2)$$

$$0 = e^0 \left[A_1 \left(-\alpha + \sqrt{\alpha^2 - \omega_0^2} \right) e^0 + A_2 \left(-\alpha - \sqrt{\alpha^2 - \omega_0^2} \right) e^0 \right]$$

$$0 = A_1 \left(-\alpha + \sqrt{\alpha^2 - \omega_0^2} \right) + A_2 \left(-\alpha - \sqrt{\alpha^2 - \omega_0^2} \right)$$

$$0 = -\alpha (A_1 + A_2) + \left(A_1 \sqrt{\alpha^2 - \omega_0^2} - A_2 \sqrt{\alpha^2 - \omega_0^2} \right)$$

$$0 = CE\alpha + \left(A_1 \sqrt{\alpha^2 - \omega_0^2} - (-A_1 - CE) \sqrt{\alpha^2 - \omega_0^2} \right)$$

$$0 = CE\alpha + \left(A_1 \sqrt{\alpha^2 - \omega_0^2} - (-A_1 - CE) \sqrt{\alpha^2 - \omega_0^2} \right)$$

$$0 = \alpha CE + 2A_1 \sqrt{\alpha^2 - \omega_0^2} + CE \sqrt{\alpha^2 - \omega_0^2}$$

$$2A_1 \sqrt{\alpha^2 - \omega_0^2} = -CE \left(\alpha + \sqrt{\alpha^2 - \omega_0^2} \right)$$

$$A_1 = -CE \left(\frac{\alpha}{2\sqrt{\alpha^2 - \omega_0^2}} + \frac{1}{2} \right) \quad (1-4)$$

(1-3)式に(1-4)式を代入

$$A_2 = -A_1 - CE \quad (1-3)$$

$$A_2 = CE \left(\frac{\alpha}{2\sqrt{\alpha^2 - \omega_0^2}} + \frac{1}{2} \right) - CE = CE \left(\frac{\alpha}{2\sqrt{\alpha^2 - \omega_0^2}} - \frac{1}{2} \right) \quad (1-5)$$

$$A_1 = -CE \left(\frac{\alpha}{2\sqrt{\alpha^2 - \omega_0^2}} + \frac{1}{2} \right) \quad (1-4)$$

$$A_2 = CE \left(\frac{\alpha}{2\sqrt{\alpha^2 - \omega_0^2}} - \frac{1}{2} \right) \quad (1-5)$$

$$q = CE + e^{-\alpha t} \left(A_1 e^{(\sqrt{\alpha^2 - \omega_0^2})t} + A_2 e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right) \quad (1-1)$$

(1-4), (1-5)式を(1-1)式に代入

$$\begin{aligned} q &= CE + e^{-\alpha t} \left(-CE \left(\frac{\alpha}{2\sqrt{\alpha^2 - \omega_0^2}} + \frac{1}{2} \right) e^{(\sqrt{\alpha^2 - \omega_0^2})t} \right. \\ &\quad \left. + CE \left(\frac{\alpha}{2\sqrt{\alpha^2 - \omega_0^2}} - \frac{1}{2} \right) e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right) \\ &= CE \left[1 + e^{-\alpha t} \left\{ - \left(\frac{\alpha}{2\sqrt{\alpha^2 - \omega_0^2}} + \frac{1}{2} \right) e^{(\sqrt{\alpha^2 - \omega_0^2})t} + \left(\frac{\alpha}{2\sqrt{\alpha^2 - \omega_0^2}} - \frac{1}{2} \right) e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right\} \right] \end{aligned}$$

$$q = CE \left[1 + e^{-\alpha t} \left\{ - \left(\frac{\alpha}{2\sqrt{\alpha^2 - \omega_0^2}} + \frac{1}{2} \right) e^{(\sqrt{\alpha^2 - \omega_0^2})t} + \left(\frac{\alpha}{2\sqrt{\alpha^2 - \omega_0^2}} - \frac{1}{2} \right) e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right\} \right]$$

$$= CE \left[1 + \frac{e^{-\alpha t}}{2} \left\{ - \left(\frac{\alpha}{\sqrt{\alpha^2 - \omega_0^2}} + 1 \right) e^{(\sqrt{\alpha^2 - \omega_0^2})t} + \left(\frac{\alpha}{\sqrt{\alpha^2 - \omega_0^2}} - 1 \right) e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right\} \right]$$

電流

$$i = \frac{dq}{dt}$$

$$i = \frac{CE}{2} \left[-\alpha e^{-\alpha t} \left\{ - \left(\frac{\alpha}{\sqrt{\alpha^2 - \omega_0^2}} + 1 \right) e^{(\sqrt{\alpha^2 - \omega_0^2})t} + \left(\frac{\alpha}{\sqrt{\alpha^2 - \omega_0^2}} - 1 \right) e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right\} \right.$$

$$\left. e^{-\alpha t} \left\{ - \left(\alpha + \sqrt{\alpha^2 - \omega_0^2} \right) e^{(\sqrt{\alpha^2 - \omega_0^2})t} + \left(-\alpha + \sqrt{\alpha^2 - \omega_0^2} \right) e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right\} \right]$$

$$= \frac{CE}{2} \left[e^{-\alpha t} \left\{ \left(\frac{\alpha^2}{\sqrt{\alpha^2 - \omega_0^2}} - \sqrt{\alpha^2 - \omega_0^2} \right) e^{(\sqrt{\alpha^2 - \omega_0^2})t} + \left(\frac{-\alpha^2}{\sqrt{\alpha^2 - \omega_0^2}} + \sqrt{\alpha^2 - \omega_0^2} \right) e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right\} \right]$$

$$= \frac{\omega_0^2}{\sqrt{\alpha^2 - \omega_0^2}} e^{-\alpha t} e^{(\sqrt{\alpha^2 - \omega_0^2})t} - \frac{\omega_0^2}{\sqrt{\alpha^2 - \omega_0^2}} e^{-\alpha t} e^{(-\sqrt{\alpha^2 - \omega_0^2})t}$$

$$\begin{aligned}
i &= \frac{CE}{2} \left[e^{-\alpha t} \left\{ \frac{\omega_0^2}{\sqrt{\alpha^2 - \omega_0^2}} e^{(\sqrt{\alpha^2 - \omega_0^2})t} - \frac{\omega_0^2}{\sqrt{\alpha^2 - \omega_0^2}} e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right\} \right. \\
&= \frac{CE}{2} \frac{\omega_0^2}{\sqrt{\alpha^2 - \omega_0^2}} \left[e^{-\alpha t} \left\{ e^{(\sqrt{\alpha^2 - \omega_0^2})t} - e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right\} \right. \\
&= \frac{\frac{1}{LC}}{\sqrt{\left(\frac{R}{2L}\right)^2 - \frac{1}{LC}}} = \frac{\frac{1}{C}}{\sqrt{\left(\frac{R}{2}\right)^2 - \frac{L}{C}}} \\
&= \frac{CE}{2} \frac{\omega_0^2}{\sqrt{\alpha^2 - \omega_0^2}} e^{-\alpha t} \left\{ e^{(\sqrt{\alpha^2 - \omega_0^2})t} - e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right\} \\
&= \frac{CE}{2} \frac{\frac{1}{C}}{\sqrt{\left(\frac{R}{2}\right)^2 - \frac{L}{C}}} e^{-\alpha t} \left\{ e^{(\sqrt{\alpha^2 - \omega_0^2})t} - e^{(-\sqrt{\alpha^2 - \omega_0^2})t} \right\} \\
&= \frac{E}{\sqrt{\left(\frac{R}{2}\right)^2 - \frac{L}{C}}} e^{-\alpha t} \frac{e^{(\sqrt{\alpha^2 - \omega_0^2})t} - e^{(-\sqrt{\alpha^2 - \omega_0^2})t}}{2} \\
&= \frac{E}{\sqrt{\left(\frac{R}{2}\right)^2 - \frac{L}{C}}} e^{-\alpha t} \sinh \left(\sqrt{\alpha^2 - \omega_0^2} \right) t
\end{aligned}$$

【問題41.4】

(3) 虚数根を持つ場合 $\left(R^2 < \frac{4L}{C}\right)$

$$\begin{aligned} p_1, p_2 &= \frac{-R \pm \sqrt{R^2 - 4\frac{L}{C}}}{2L} = \frac{-R \pm j\sqrt{4\frac{L}{C} - R^2}}{2L} \\ &= -\frac{R}{2L} \pm j\sqrt{\frac{1}{LC} - \left(\frac{R}{2L}\right)^2} = -\alpha \pm j\omega \end{aligned}$$

$$\begin{aligned} q_t &= A_1 e^{p_1 t} + A_2 e^{p_2 t} \\ &= A_1 e^{(-\alpha + j\omega)t} + A_2 e^{(-\alpha - j\omega)t} \\ &= e^{-\alpha t} (A_1 e^{j\omega t} + A_2 e^{-j\omega t}) \end{aligned}$$

一般解

$$\begin{aligned}q &= q_s + q_t \\&= CE + e^{-\alpha t} (A_1 e^{j\omega t} + A_2 e^{-j\omega t}) \\&= CE + e^{-\alpha t} [A_1 (\cos \omega t + j \sin \omega t) + A_2 (\cos \omega t - j \sin \omega t)] \\&= CE + e^{-\alpha t} [(A_1 + A_2) \cos \omega t + j(A_1 - A_2) \sin \omega t] \quad (2-1)\end{aligned}$$

電流

$$\begin{aligned}i &= \frac{dq}{dt} = -\alpha e^{-\alpha t} ((A_1 + A_2) \cos \omega t + j(A_1 - A_2) \sin \omega t) \\&\quad + e^{-\alpha t} (-(A_1 + A_2)\omega \sin \omega t + j\omega(A_1 - A_2) \cos \omega t) \\&= e^{-\alpha t} [\{-\alpha(A_1 + A_2) + j\omega(A_1 - A_2)\} \cos \omega t \\&\quad + \{-(A_1 + A_2)\omega - j\alpha(A_1 - A_2)\} \sin \omega t] \quad (2-2)\end{aligned}$$

初期条件 $t = 0, q = 0, i = 0$

(2-1)式に $t = 0, q = 0$ を代入

$$q = CE + e^{-\alpha t} [(A_1 + A_2) \cos \omega t + j(A_1 - A_2) \sin \omega t] \quad (2-1)$$

$$0 = CE + e^0 [(A_1 + A_2) \cos 0 + j(A_1 - A_2) \sin 0]$$

$$A_1 + A_2 = -CE \quad (2-3) \quad = 0$$

(2-2)式に $t = 0, i = 0$ を代入

$$i = e^{-\alpha t} [\{-\alpha(A_1 + A_2) + j\omega(A_1 - A_2)\} \cos \omega t + \{-(A_1 + A_2)\omega - j\alpha(A_1 - A_2)\} \sin \omega t] \quad (2-2)$$

$$0 = e^0 [\{-\alpha(A_1 + A_2) + j\omega(A_1 - A_2)\} \cos 0 + \{-(A_1 + A_2)\omega - j\alpha(A_1 - A_2)\} \sin 0]$$

$$0 = -\alpha(A_1 + A_2) + j\omega(A_1 - A_2) \quad (2-4) \quad = 0$$

$$0 = -\alpha(A_1 + A_2) + j\omega(A_1 - A_2) \quad (2-4)$$

$$j\omega(A_1 - A_2) = \alpha(A_1 + A_2)$$

$$j(A_1 - A_2) = \frac{\alpha(A_1 + A_2)}{\omega} = \frac{\alpha(-CE)}{\omega} \quad (2-5)$$

(2-1)式に(2-4)式, (2-5)式を代入

$$\begin{aligned} q &= CE + e^{-\alpha t} [(A_1 + A_2) \cos \omega t + j(A_1 - A_2) \sin \omega t] \\ &= CE + e^{-\alpha t} \left[-CE \cos \omega t - \frac{\alpha CE}{\omega} \sin \omega t \right] \\ &= CE \left[1 - e^{-\alpha t} \left(\cos \omega t + \frac{\alpha}{\omega} \sin \omega t \right) \right] \\ &= CE \left[1 - e^{-\alpha t} \left(\frac{\alpha}{\omega} \sin \omega t + \cos \omega t \right) \right] \quad (2-6) \end{aligned}$$

$$q = CE \left[1 - e^{-\alpha t} \left(\frac{\alpha}{\omega} \sin \omega t + \cos \omega t \right) \right] \quad (2-6)$$

$$\frac{\alpha}{\omega} \sin \omega t + \cos \omega t = \sqrt{\left(\frac{\alpha}{\omega}\right)^2 + 1^2} \cdot \sin(\omega t + \theta_1) \quad \tan \theta_1 = \frac{1}{\frac{\alpha}{\omega}} = \frac{\omega}{\alpha}$$

【公式】 $a \sin \omega t + b \cos \omega t = \sqrt{a^2 + b^2} \sin(\omega t + \theta)$

$$\tan \theta = \frac{b}{a}$$

ここで

$$\left(\frac{\alpha}{\omega}\right)^2 = \frac{\left(\frac{R}{2L}\right)^2}{\frac{1}{LC} - \left(\frac{R}{2L}\right)^2} = \frac{1}{\frac{1}{LC} \frac{4L^2}{R^2} - 1} = \frac{1}{\frac{4L}{CR^2} - 1}$$

より

$$\sqrt{\left(\frac{\alpha}{\omega}\right)^2 + 1^2} = \sqrt{\frac{1}{\frac{4L}{CR^2} - 1} + 1} = \sqrt{\frac{\frac{4L}{CR^2}}{\frac{4L}{CR^2} - 1}} = \sqrt{\frac{1}{\frac{CR^2}{4L} - 1}}$$

$$q = CE \left[1 - e^{-\alpha t} \frac{1}{\sqrt{\frac{CR^2}{4L} - 1}} \sin(\omega t + \theta_1) \right]$$

$$q = CE \left[1 - e^{-\alpha t} \frac{1}{\sqrt{\frac{CR^2}{4L} - 1}} \sin(\omega t + \theta_1) \right]$$

$$i = \frac{dq}{dt}$$

$$= CE \left[\alpha e^{-\alpha t} \frac{1}{\sqrt{\frac{CR^2}{4L} - 1}} \sin(\omega t + \theta_1) - e^{-\alpha t} \frac{1}{\sqrt{\frac{CR^2}{4L} - 1}} \omega \cos(\omega t + \theta_1) \right]$$

$$= CE \frac{1}{\sqrt{\frac{CR^2}{4L} - 1}} e^{-\alpha t} [\alpha \sin(\omega t + \theta_1) - \omega \cos(\omega t + \theta_1)]$$

$$= CE \frac{1}{\sqrt{\frac{CR^2}{4L} - 1}} e^{-\alpha t} \left[\sqrt{\alpha^2 + \omega^2} \sin(\omega t + \theta_1 + \theta_2) \right]$$

$$\tan \theta_1 = \frac{\omega}{\alpha}$$

$$\tan \theta_2 = -\frac{\omega}{\alpha}$$

ここで

$$\tan(\theta_1 + \theta_2) = \frac{\tan \theta_1 + \tan \theta_2}{1 - \tan \theta_1 \tan \theta_2} = 0$$

$$\tan \theta_1 = \frac{\omega}{\alpha}$$
$$\tan \theta_2 = -\frac{\omega}{\alpha}$$

より

$$\theta_1 + \theta_2 = 0$$

よって

$$i = CE \frac{1}{\sqrt{\frac{CR^2}{4L} - 1}} e^{-\alpha t} \left[\sqrt{\alpha^2 + \omega^2} \sin(\omega t) \right]$$

【問題41.5】

第4章：過渡現象

4.4 過渡現象の解法

キーワード：*RLC*直列回路

学習目標：*RLC*直列回路の過渡現象を解くことができるようになる。